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## ON CERTAIN EXACT SOLUTIONS OF THE FOURIER EQUATION FOR REGIONS VARYING WITH TIME

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1. Let us use the method given in [1] to solve the first boundary value problem for the three-dimensional Fourier equation in Cartesian coordinates

$$
\begin{equation*}
\sum_{i=1}^{n} \frac{\hat{o}^{2} U}{\partial x_{i}^{2}}=\frac{\partial U}{\partial t}+f\left(x_{1}, \ldots, x_{n}, t\right) \quad(n=1,2,3) \tag{1.1}
\end{equation*}
$$

defined on the domain bounded by coordinate planes moving in accordance with some rules $R_{i}^{(1)}(t)$ and $R_{i}^{(1)}$ ( $t$ so that

$$
x_{i} \in\left(R_{i}^{(n)}(t), R_{i}^{(1)}(t)\right)
$$

where $i$ denote the coordinate axis number. Assume that the functions $R_{1}^{(0)}$ and $R_{1}^{(1)}$ possess continuous first and second order derivatives. We then obtain

$$
\begin{align*}
& \sum_{i=1}^{n} \frac{1}{\eta_{i}{ }^{2}}\left[\frac{\left.\partial^{2}\right|^{\cdot}}{\partial y_{i}{ }^{2}}+\frac{1}{4}\left(\eta_{i}{ }^{8} \eta_{i} \ddot{ }^{\prime} y_{i}{ }^{2}+2 \eta_{i}{ }^{8} R_{i}{ }^{(0) \cdot} y_{i}\right) \Gamma\right]=\frac{\partial l}{d t}+\frac{j}{\eta}  \tag{1.2}\\
& \|=q\left(y_{1}, \ldots, y_{n}, t\right) V^{\prime}\left(y_{1}, \ldots, y_{n}, t\right), \quad y_{i}=\frac{x_{i}-h_{i}^{(0)}}{\eta_{i}} \quad\left(\eta_{i}=R_{i}^{(1)}-R_{i}^{(0)}\right) \tag{1.3}
\end{align*}
$$

$$
q=\prod_{i=1}^{n} \frac{1}{\sqrt{\eta_{i}}} \exp \left[-\frac{1}{4}\left(\eta_{i} \eta_{i} y_{i}^{2}+2 \eta_{i} R_{i}^{(0)^{*}} y_{i}+\int\left(R_{i}^{(0)^{*}}\right)^{2} d t\right], \quad y_{i} \in(0,1)\right.
$$

Equation (1.2) admits an exact solution in the terms of well-known functions, provided that the following conditions hold simultaneously for all :
if

$$
\eta_{i}{ }^{9} \eta_{i}{ }^{* *}=\text { const }, \quad \eta_{i}^{3} R_{i}{ }^{(0)^{*}}=\text { const }
$$

(1)
or

$$
\begin{equation*}
\eta_{i}=\text { const }, \quad R_{i}^{(0)}=M_{i} t^{2}+A_{i} t+B_{i} \tag{1.4}
\end{equation*}
$$

(2) $\eta_{i}=\sqrt{M_{i} t^{2}+A_{i} l+B_{i}}, \quad R_{i}^{(0)}=C_{i} \sqrt{M_{i} t^{2}+A_{i} t+B_{i}}+D_{i} t+E_{i}$
or

$$
\begin{equation*}
\eta_{i}=A_{i} t+B_{i}, \quad R_{i}^{(0)}=\frac{C_{i}}{A_{i} t+B_{i}}+D_{i} t+F_{i} \tag{1.5}
\end{equation*}
$$

Here $A_{i}, B_{i}, C_{i}, D_{i}, E_{i}, M_{i}$ are constants depending on $i$. Particular cases of the motions represented by (1.4) and (1.5) have been obtained in [1-3].
2. If the domain is given in the cylindrical coordinate system and is bounded by planes in the $z$-direction and by surfaces moving according to the rules

$$
z=R_{8}^{(0)}(t), \quad z=R_{3}^{(1)}(t) ; \quad r=R_{1}(t), \quad r=R_{2}(t) \equiv a R_{1}(t) \quad(\alpha=\text { const })
$$

in the $r$-direction, then the proposed method transforms the Fourier equation in $U$ into the following equation written in terms of another function $V$ :

$$
\begin{gather*}
\frac{1}{R_{1}^{2}}\left[\frac{1}{y_{1}} \frac{\partial}{\partial y_{1}} y_{1} \frac{\partial V}{\partial y_{1}}+\frac{1}{4} y_{1}^{2} R_{1}^{8} R_{1}^{\cdot} V+\frac{1}{y_{1}^{2}} \frac{\partial^{2} V}{\partial \varphi^{2}}\right]+ \\
+\frac{1}{\eta^{2}}\left[\frac{\partial^{2} V}{\partial y_{3}^{2}}+\frac{1}{4}\left(\eta^{8} \eta^{\bullet} y_{2}^{3}+2 \eta^{3} R_{2}{ }^{(0)} y_{3}\right) V\right]=\frac{\partial V}{\partial t}+\frac{f\left(y_{1} R_{1}, \varphi, y_{3} \eta, t\right)}{q} \tag{2.1}
\end{gather*}
$$

where

$$
\begin{gather*}
U=q\left(y_{1}, y_{3}, t\right) V\left(y_{1}, \varphi, y_{3}, t\right)  \tag{2.2}\\
y_{1}=\frac{r}{R_{1}} \quad\left(y_{1} \in(\alpha, 1)\right), \quad y_{3}=\frac{x_{3}-R_{3}{ }^{(0)}}{\eta} \quad\left(\eta \doteq R_{3}^{(1)}-R_{8}{ }^{(0)}\right) \\
q=\frac{1}{R_{1} \sqrt{\eta}} \exp \left[-\frac{1}{4}\left(y_{1}^{2} R_{1} R_{1}{ }^{0}+\eta \eta^{0} y_{3}{ }^{2}+2 \eta R_{3}{ }^{(0)} y_{3}+\int\left(R_{3}{ }^{(0)^{0}}\right)^{2} d t\right)\right]
\end{gather*}
$$

Equation (2.1) admits an exact solution in the terms of well-known functions provided that the conditions

$$
\begin{equation*}
R_{1}^{3} R_{1}{ }^{\bullet}=\text { const }, \quad \eta^{3} \eta^{\bullet}=\text { const }, \quad \eta^{3} R_{3}^{(0)^{* *}}=\text { const } \tag{2.3}
\end{equation*}
$$

hold simultaneously when

$$
\begin{equation*}
R_{1}=\sqrt{M_{1} t^{2}+A_{1} t+B_{1}}, \quad R_{2}=\alpha R_{1} \quad\left(\alpha, A_{1}, B_{1}, M_{1}=\text { const }\right) \tag{2.4}
\end{equation*}
$$

while $R_{3}^{(0)}$ and $R_{a}^{(1)}$ satisfy the equations of motion of the type (1.4)-(1.6).
We note that the domains defined above include in particular the following ones:
a) a parallelepiped, one parallel pair of faces of which moves in the relevant axial direction according to (1.4), the second pair according to (1.5) and the third pair according to (1.6);
b) a bounded hollow cylinder whose side surfaces follow (2.4) and the end-walls any
one of (1.4), (1.5) or (1.6).
3. Obviously, when the domain consists of a spherical symmetrical layer bounded by spherical surfaces, the equations of motion of which coincide with either (1.4) or (1.5) or (1.6), application of the same procedure yields an exact solution of the initial problem in spherical coordinates, as the substitution $W=U / r$ ( $r$ is the coordinate and $W$ is the new function) transforms the equation

$$
\frac{1}{r^{2}} \frac{\partial}{\partial r} r^{2} \frac{\partial U}{\partial r}=\frac{\partial U}{\partial t}+f(r, t)
$$

into (1.1) which has been already considered.

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